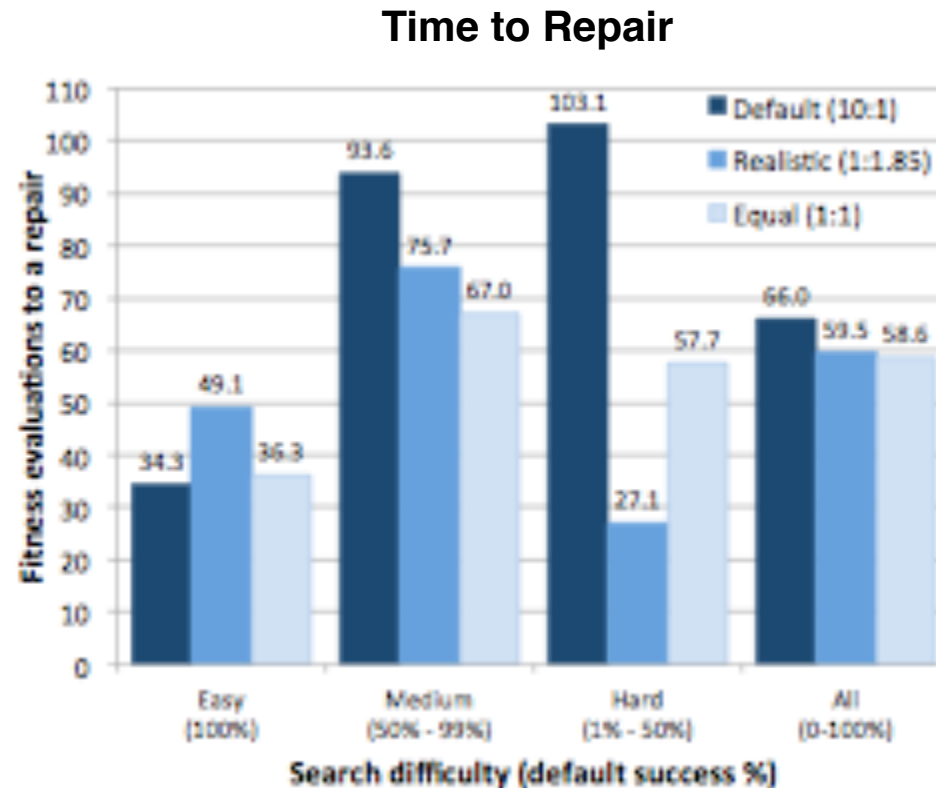


- See Karl after class in CS computer lab if you have a question about your code grade
- See me or Mathew if you have a question about your report grade **AFTER filling in rubric & examples.**
- If you got <75%, office hrs Th am, Mon pm. Also writing tutors at Office of Grad Studies.
- Meet after class if you need a partner for Project 2
- Send presentation slides to Matthew

GAs

- Claire LeGoues talk
 - Weighted path & constraining the search space
 - GAs challenge assumptions by finding bizarre solutions
 - Crossover
 - Fuzz testing & real-world automated repair for security vulnerabilities
- Natural selection
 - has No Goal
 - operates at multiple levels
 - evolves robustness & evolvability
- Project 2 Part 2
 - evolve cooperation & maybe competition
 - code is in C++

Weighted Path Schemes



Conclude: Both new weighting schemes cause the GP to repair a bug on which the default weighting scheme failed.



Mitchell Chapter 10

- Living systems compute
- Living systems are open systems that exchange energy, materials & information
 - E.g. Erwin Shrodinger (1944) & Lynn Margulis (200) books:
What is Life? discuss how life creates order from disorder
- Computation is what a complex system does to adapt to its environment
- Life *is* computation?
- Cellular Automata: simplified demonstrations of how life might compute

Rule 110

0	0	0	→	0
0	0	1	→	1
0	1	0	→	1
0	1	1	→	1
1	0	0	→	0
1	0	1	→	1
1	1	0	→	1
1	1	1	→	0

Read the bit string BOTTOM to TOP

111 is leftmost (most significant) bit

000 is the least significant bit

000	001	010	011	100	101	110	111
0	1	1	1	0	1	1	0

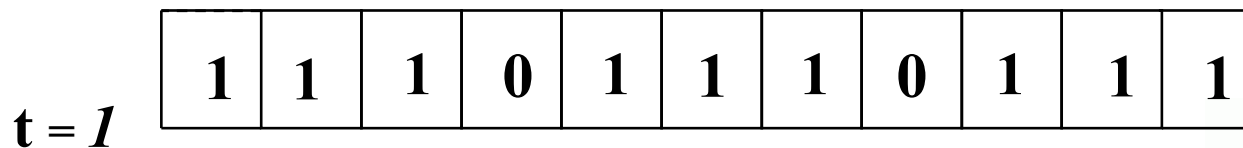
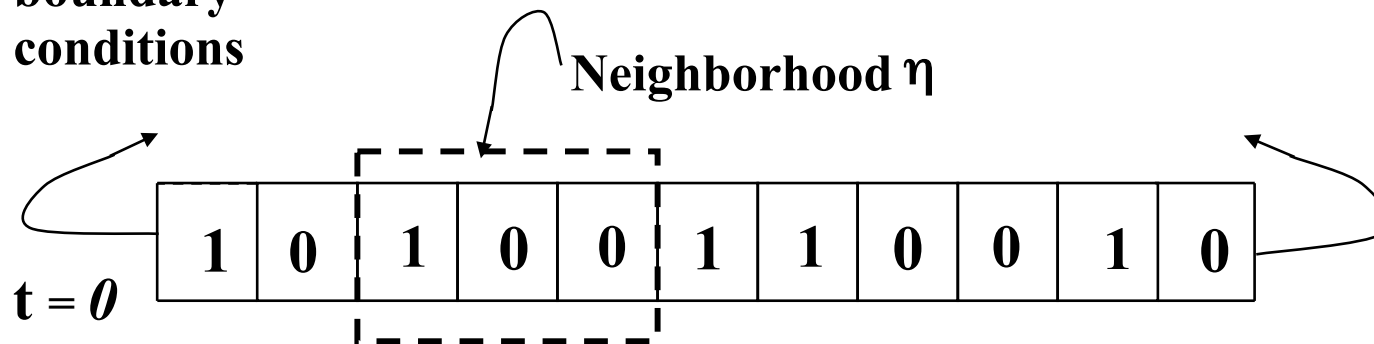
$$01101110 = 0 + 2 + 4 + 8 + 0 + 32 + 64 = \text{Rule 110}$$

Rule Table ϕ :

Neighborhood:	000	001	010	011	100	101	110	111
Output bit:	0	1	1	1	0	1	1	0

Lattice:

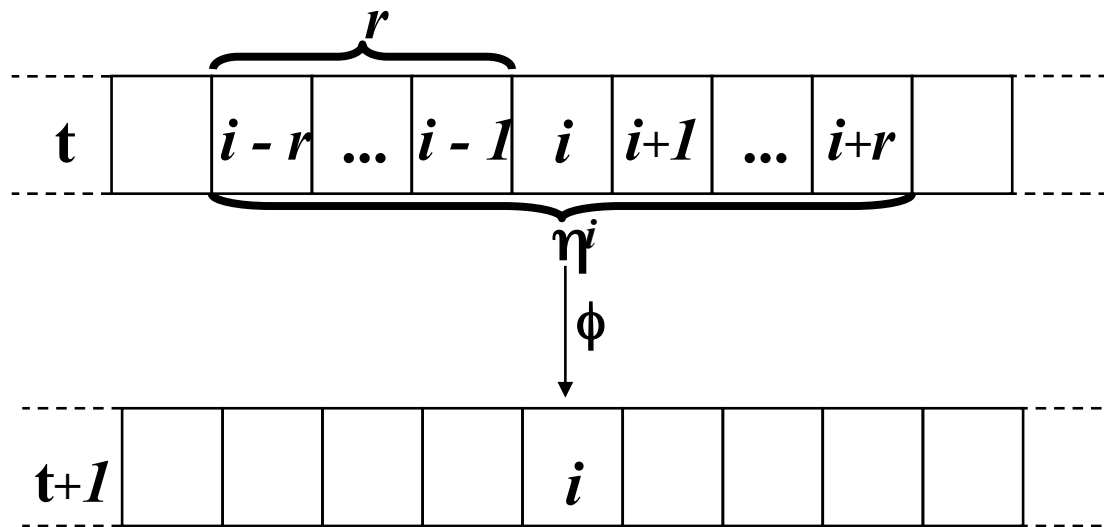
Periodic
boundary
conditions



Introduction to Cellular Automata (CA)

- Invented by John von Neumann (circa~1950).
- A cellular automata consists of:
 - A regular arrangement (lattice) of cells.
 - Cells can be in one of a finite number of states at each time step.
 - All cells have the same synchronous update rule.
 - Cells have a local interaction neighborhood.
- Example: The game of life.
- Many cellular automata applications:
 - Hydrodynamics, fluid dynamics
 - Forest fire simulation
 - Models of ecosystems and epidemics
 - Ferro-magnetic modeling (ISING models)

One-Dimensional CA Illustration



One-Dimensional Cellular Automaton (CA)

- Consists of a linear array of identical *cells* (called a *lattice*), each of which can be in a finite number of k states.
- The (local) *state* of cell i at time t is denoted: $s_t^i \in \Sigma = \{0, 1, \dots, k - 1\}$
- The (global) state s_t at time t is the *configuration* of the entire array,
$$s_t = (s_t^0, s_t^1, \dots, s_t^{N-1}) \in \Sigma^N$$
- where N is the (possibly infinite) size of the array.

One-Dimensional CA cont.

- At each time step, all cells in the array update their state simultaneously, according to a *local update rule* $\phi: \eta \rightarrow s$.
- This update rule takes as input the *local neighborhood configuration* η of a cell.
- A local neighborhood configuration η consists of s_i and its $2r$ nearest neighbors (r cells on either side):

$$\eta_i = (s^{i-r}, \dots, s_i, \dots, s^{i+r})$$

- r is called the *radius* of the CA.
- The local update rule ϕ
 - is the same for every cell in the array
 - Represented as a lookup table, with all neighborhood configurations
- The state of each cell at time $t+1$ is determined by applying ϕ to each cell at time t :

$$s_{t+1}^i = \phi(\eta_t^i)$$

Rule 110

0	0	0	→	0
0	0	1	→	1
0	1	0	→	1
0	1	1	→	1
1	0	0	→	0
1	0	1	→	1
1	1	0	→	1
1	1	1	→	0

The number of rules in the rule table is the number of neighborhood configurations

$$(|\eta| = k^{2r+1})$$

Each rule can map to one of k states, so

The number of possible rules is

$$k^{2r+1}$$

k

000	001	010	011	100	101	110	111
0	1	1	1	0	1	1	0

0 1 1 0 1 1 1 0 = 0 + 2 + 4 + 8 + 0 + 32 + 64 = Rule 110

Read the bit string BOTTOM to TOP

Example One-Dimensional CA

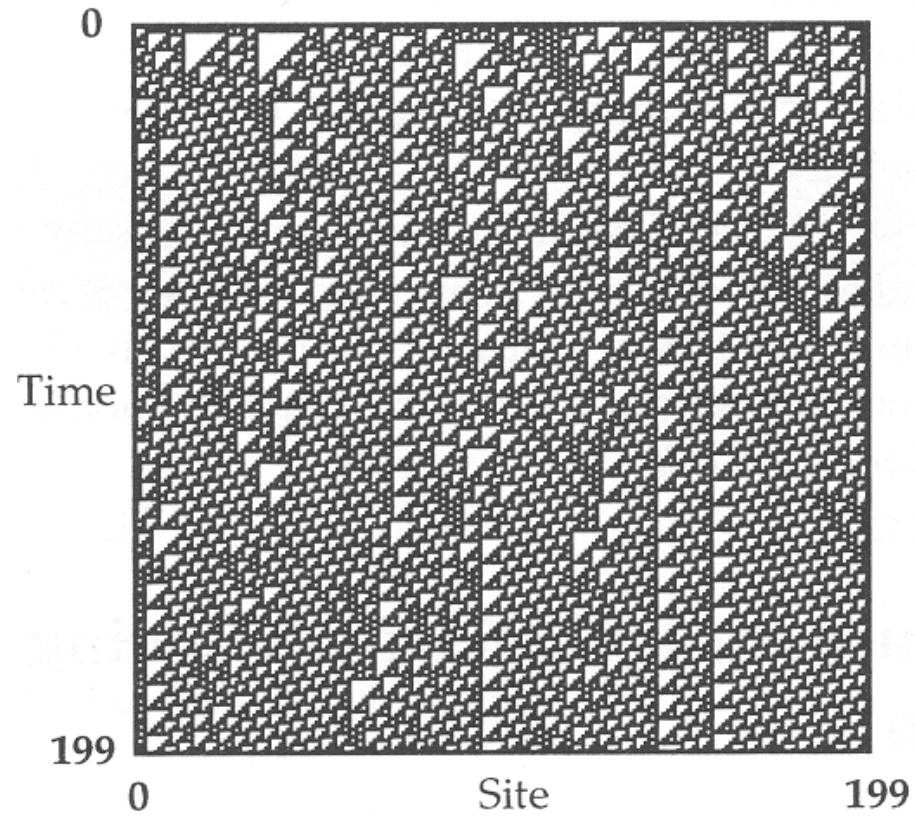
Rule 110

- The number of states, $k=2$.
- The alphabet $\Sigma = \{0,1\}$ $|\Sigma| = k$
- The size of the array, $N=11$.
- The configuration space η
 $\Sigma^N = \{(0,0,0,0,0,0,0,0,0,0,0), (0,0,0,0,0,0,0,0,0,0,0,11), \dots\}$
- The radius $r = 1$.
- The rule table $s_{t+1}^i = \phi(\eta_t^i)$
 k^{2r+1} neighborhood configurations in ϕ

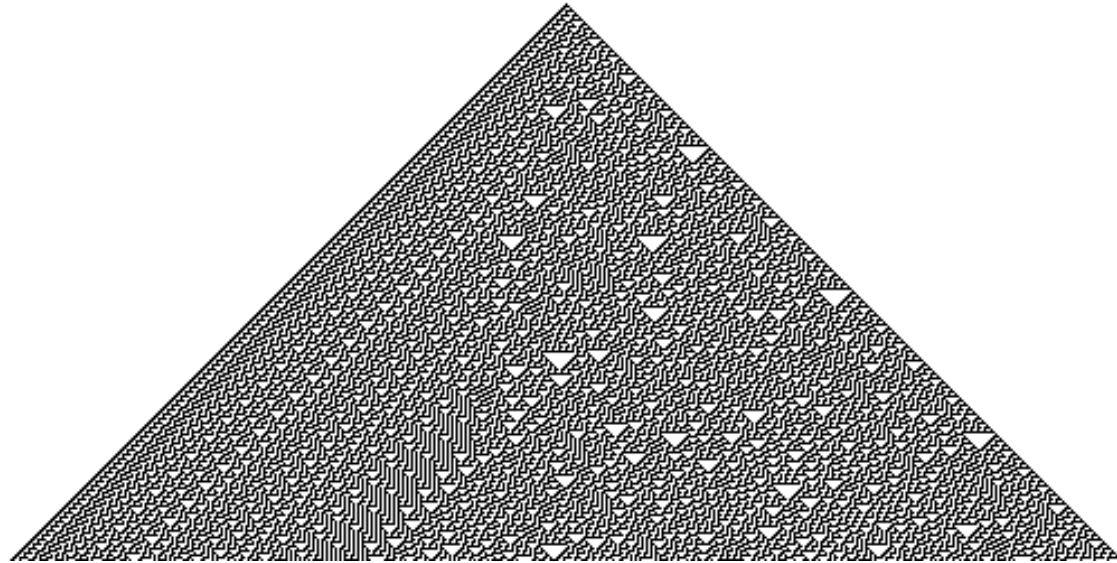
000	001	010	011	100	101	110	111
0	1	1	1	0	1	1	0

- In Wolfram notation this is rule 110 (base 10) because the output states are: 01101110 (base 2).
- Rule 110 supports universal computation.

Rule 110 Space-Time Plot



Rule 30



current pattern

111 110 101 100 011 010 001 000

new state for center cell

0 0 0 1 1 1 1 0

Comments on Rule 30

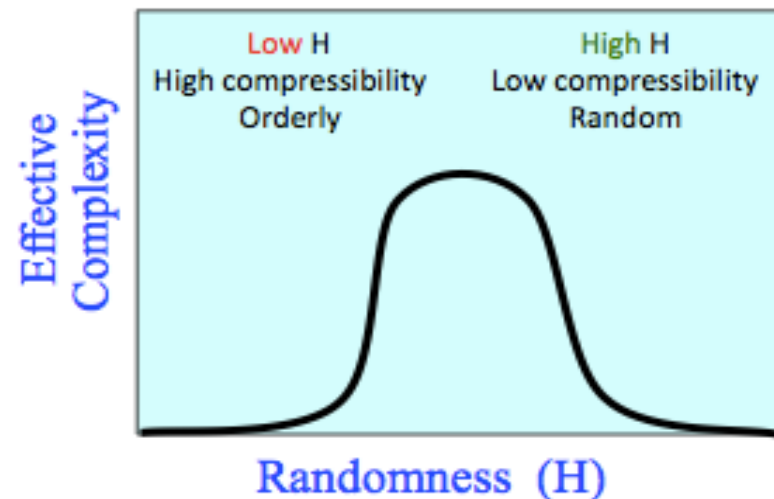
- Generates apparent randomness, despite being finite
- Wolfram uses the central column as a pseudo-random number generator in Mathematica
- Passes many tests for randomness, but many inputs produce regular patterns:
 - All zeroes
 - 00001000111000 repeated infinitely (try separating by 6 1s)

Wolfram's CA Classification

- **Class I:** Eventually every cell in the array settles into one state, never to change again. Analogous to
 - computer programs that halt after a few steps
 - dynamical systems that have fixed-point attractors
- **Class II:** Eventually the array settles into a periodic cycle of states
 - computer programs that execute infinite loops
 - dynamical systems that fall into limit cycles.
- **Class III:** The array forms “aperiodic” random-like patterns.
 - computer programs that are pseudo-random number generators (pass most tests for randomness, highly sensitive to seed, or initial condition).
 - Analogous to chaotic dynamical systems. Deterministic but almost never repeat themselves, sensitive to initial conditions, embedded unstable limit cycles.

Wolfram's Classification cont.

- Class IV: The array forms *complex* patterns with localized structure that move through space and time:
 - Difficult to describe. Not regular, not periodic, not random.
 - Speculate that it is interesting computation.
- Hypothesis: The most interesting and complex behavior occurs in Class IV CA---"the edge of chaos".
- Example: Rule 110



Wolfram Class I

00040001002000200020030000004	00100001000000200001030000014	00001001000000200400030100004

Figure 15.5 Examples of Wolfram's Class I

Figure from *The Computational Beauty of Nature: Computer Explorations of Fractals, Chaos, Complex Systems, and Adaptation*. Copyright © 1998–2000 by Gary William Flake. All rights reserved. Permission granted for educational, scholarly, and personal use provided that this notice remains intact and unaltered. No part of this work may be reproduced for commercial purposes without prior written permission from the MIT Press.

Wolfram Class II

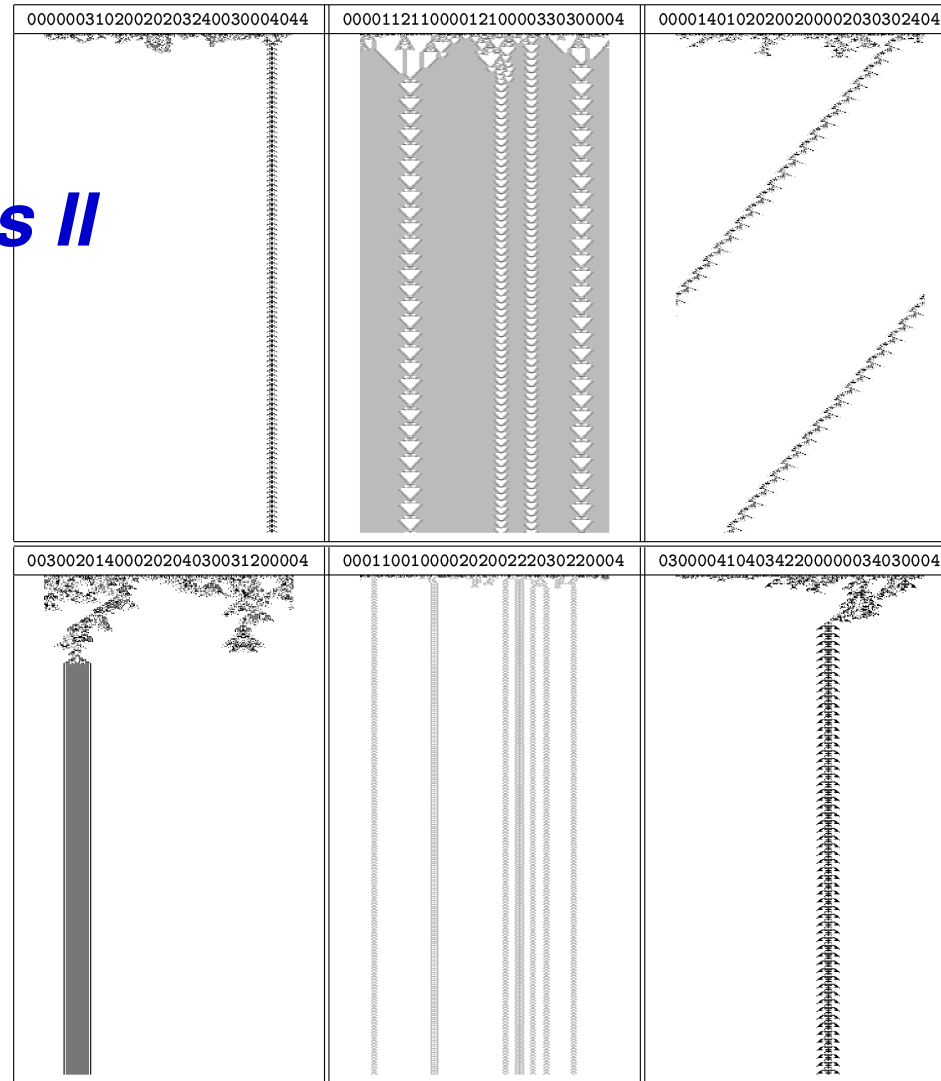


Figure 15.6 Examples of Wolfram's Class II

Figure from *The Computational Beauty of Nature: Computer Explorations of Fractals, Chaos, Complex Systems, and Adaptation*. Copyright © 1998–2000 by Gary William Flake. All rights reserved. Permission granted for educational, scholarly, and personal use provided that this notice remains intact and unaltered. No part of this work may be reproduced for commercial purposes without prior written permission from the MIT Press.



Wolfram Class III

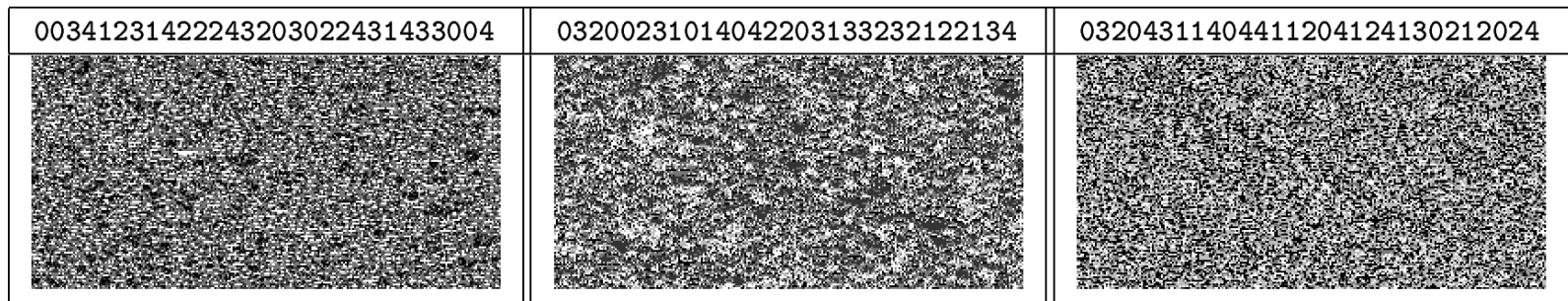


Figure 15.7 Examples of Wolfram's Class III

Figure from *The Computational Beauty of Nature: Computer Explorations of Fractals, Chaos, Complex Systems, and Adaptation*. Copyright © 1998–2000 by Gary William Flake. All rights reserved. Permission granted for educational, scholarly, and personal use provided that this notice remains intact and unaltered. No part of this work may be reproduced for commercial purposes without prior written permission from the MIT Press.

Wolfram Class IV

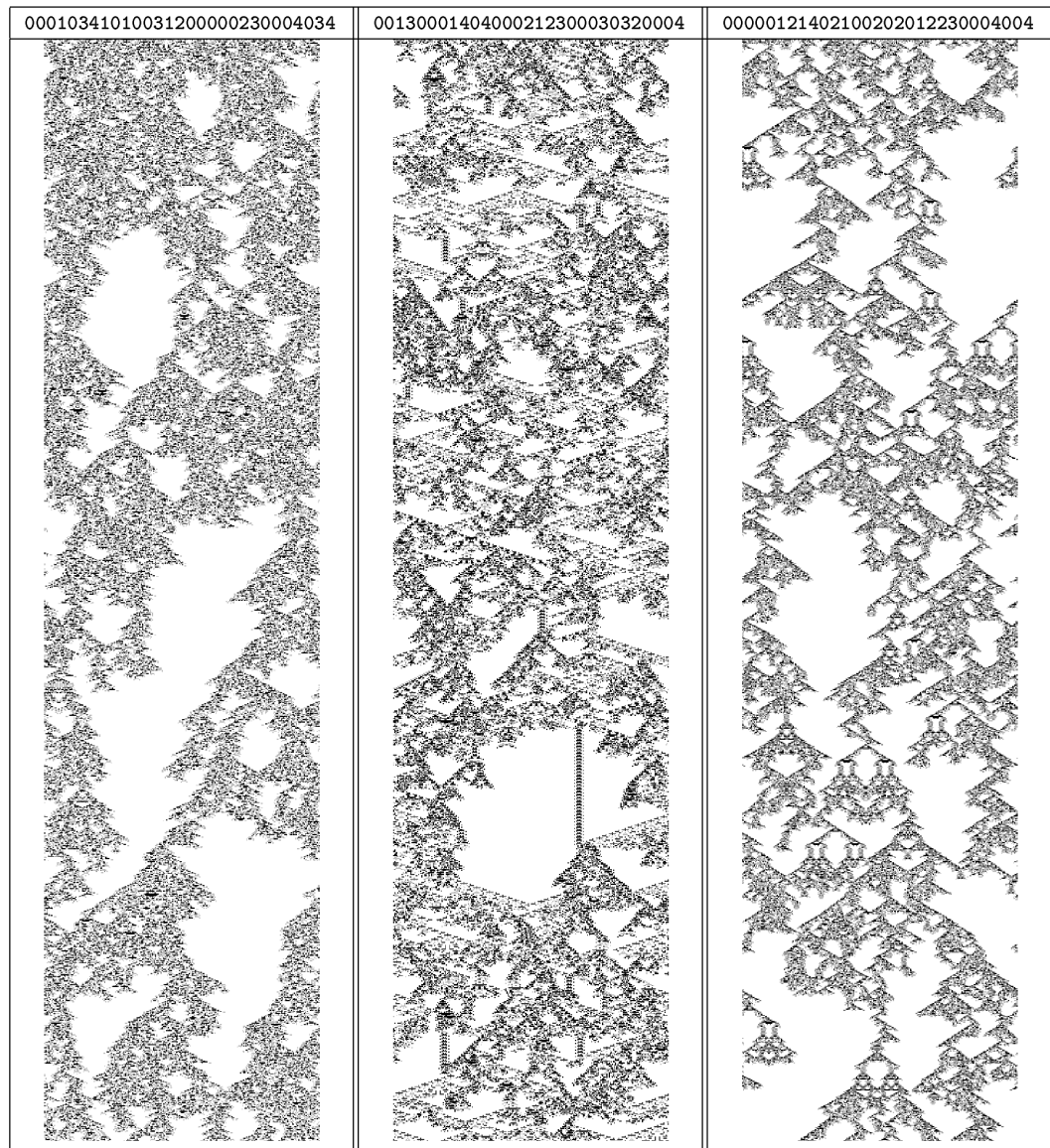


Figure 15.8 Examples of Wolfram's Class IV

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Cellular Automata as models of complexity

Wolfram *Nature* 1984

- 4 classes
 - I: Fixed point
 - II: Limit cycle
 - III: Random or chaotic (unpredictable)
 - IV: Complex
- Beyond $r = 1$ (Figs 3 – 6)
- Entropies & Dimensions
- Information Propagation
- Class IV supports universal computation (?)
 - Long-term behavior undecidable and intractable
 - Simulation is necessary



<http://twilightstarsong.blogspot.com/2009/03/shaping-future-stephen-wolfram-ray.html>

Entropies & Dimensions

Class I: no randomness in space or time (0 entropy)

Class II: randomness in space, predictable in time after a transient

Class III: unpredictable in time and space

Class IV: undecidable

Information Propagation

Class I: no information propagation

Class II: propagation in a finite region

Class III: propagation over an increasing region, at fixed speed, over time

Class IV: irregular propagation over (potentially) infinite region

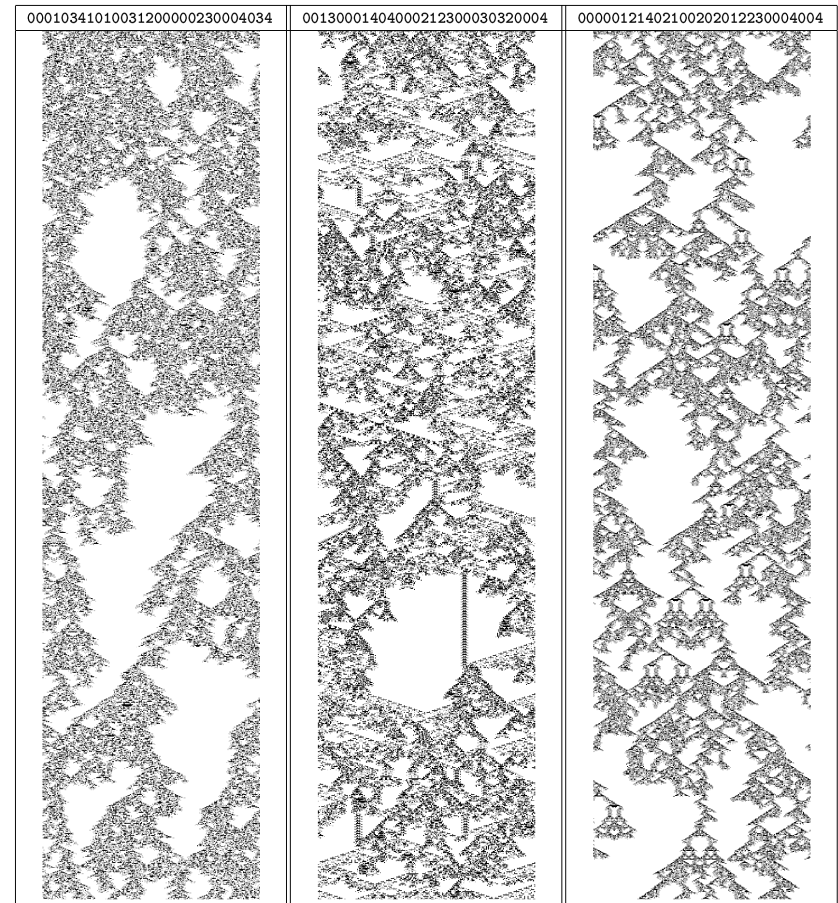


Figure 15.8 Examples of Wolfram's Class IV