

George Matthew Fricke

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Citizenship: United States, United Kingdom

EDUCATION

Doctor of Philosophy, Computer Science
with distinction

The University of New Mexico, Albuquerque, NM, May 2017
GPA: 3.85

Bachelor of Science, Mathematics

The University of New Mexico, Albuquerque, NM, May 2012
cum laude

Master of Science, Computer Science

The University of New Mexico, Albuquerque, NM, Aug. 2003

Bachelor of Art, Anthropology

Appalachian State University, Boone, NC, Dec. 1996
dean's list

PROFESSIONAL EXPERIENCE

Adjunct Professor and Technical Lead

2013-Present

Dept. of Computer Science and UNM-NASA Swarmathon,
University of New Mexico

- Software Lead promoted to Technical Lead
- Supervise eight graduate and undergraduate programmers
- Swarmathon: Responsible for all technical aspects of the UNM-NASA swarm robotics swarm robotic resource collection challenge in collaboration with Kennedy Space Center including purchasing, robot hardware development, and novel search algorithm design. This program has three components: outreach to more than 40 underserved universities and colleges and more than 50 highschools; novel aerial and ground based swarm robots, and development of swarm search algorithms for those robots.
- Immunological search: Analysis of swarm search patterns in T cells in collaboration with the UNM Health Sciences Center . Supervised a programmer and a mathematician.
- Built and maintain a Beowulf cluster using Ubuntu with NFS and LDAP for high performance data simulations.
- C++ with ROS and QT. Developed distributed robot simulation software using MPI. Matlab used for analysis.

Research Programmer

Spring 2012

Institute for Mathematics and Education, University of Arizona

- Designed and coded mathematical problems as examples of the Common Core States Standards for mathematics for the Illustrative Mathematics Project website. Funded by the Bill and Melinda Gates Foundation.

Research Programmer (Contractor)

2004-2010

Los Alamos National Labs, Los Alamos, NM

- Team leader supervising two programmers.

- Developed a biochemical reaction network generator and analyzer (BioNetGen) using Perl and Java for the Theoretical Biology Group (T10).
- Developed a web-based version of the software (GetBonnie) on using PHP, Java, and SQL under Redhat linux (LAMP).

Graduate Research Assistant 2003-2004
Department of Physics and Astronomy, University of New Mexico

- Developed a Monte-Carlo computer simulation of IgE cell signaling in C++ with Jim Thomas (UNM Physics), collected results from the model and coauthored a paper in *BioPhysical Chemistry*.

Analyst-Programmer II Summer 2002
Center for Advanced Research Computing, University of New Mexico

- Summer position working with Gregory Starr (UNM Mechanical Engineering) at the CoMeT (Computational Mechanics Toolkit) robotics group.
- Implemented Neural Networks, Fuzzy Logic Systems, and Data Flow Control Networks in order to generate robotic hand grasp parameters for nuclear waste handling in C++ and Scheme. Funded by the Department of Energy and the Idaho National Engineering and Environmental Laboratory.

Research Assistant 2001 - 2002
University of New Mexico NASA Pursue Program

- Worked in George Luger's (UNM Computer Science) lab on the design and implementation of an embodied, agent-based, robotic control system. Funded by the NASA Center for Autonomous Control Engineering.

Programmer II, Systems Analyst I 1993 - 1999
University of New Mexico Health Sciences Center, CPH and MHC.

- System administration, design, and implementation. Began as helpdesk technician II for several thousand computers in a heterogeneous network environment, promoted to systems analyst responsible for planning and administration of all computer and network systems for two UNM departments. Implemented system administration tools in Visual Basic.
- Supervised three full time employees.

Field Archaeologist 1991-93
Mariah and Associates, National Park Service, Appalachian State University

- Survey and deep excavation (Phase III) at sites in New Mexico, New York State, West Virginia and North Carolina.

TEACHING

Introduction to Programming Swarm Robots Fall 2017
University of New Mexico Computer Science Dept.

- Instructor of Record. Dual graduate and undergraduate course in Swarm Robotics. Students learn to program robots in hardware and using the Gazebo simulator. Emphasis on writing collaborative algorithms using the Robot Operating System (ROS) framework.

Complex Adaptive Systems Spring 2017
University of New Mexico Computer Science Dept.

- Instructor of Record. graduate course in Complex Adaptive Systems. We cover dynamical systems, genetic algorithms, game theory, cellular automata, and network theory.

Quantifying and Modeling T cell Motility in Lymph Nodes Summer 2016
Tenth q-bio Summer School, Albuquerque, NM

- Guest Lecturer: taught maximum likelihood analysis and distinguishing motility models.

- Mathematical Foundations of Computer Science** Summer 2013
University of New Mexico Computer Science Dept.
- Instructor of Record: Responsible for all aspects of this course in discrete math. Topics covered include proofs, set theory, logic, combinatorics, state machines, generator functions and recurrence relations.
- Complex Adaptive Systems** Spring 2013
University of New Mexico Computer Science Dept.
- Teaching Assistant: Assisted Prof. Moses in organizing, grading, and teaching this graduate level course.
- Intermediate Programming with Java** Fall 2012
University of New Mexico Computer Science Dept.
- Teaching Assistant: Lectured on Java programming, ran labs, designed and graded assignments and exams.
- Computer Programming Fundamentals with C++** Summer 2003
University of New Mexico Computer Science Dept.
- Instructor of Record. Responsible for all aspects of this course which provides engineering students with a foundation in problem solving using C++.
- Discrete Math** Spring 2002
University of New Mexico Computer Science Dept.
- Guest Lecturer: taught inference rules and proof techniques.

COMPUTER SKILLS

Languages: C++ (QT, MPI, ROS, OpenGL), Matlab, Java, Javascript, SQL, HTML5, PHP and Java web interfaces (full stack including node.js)
Systems Administration: Linux (Ubuntu, Redhat), Windows Server and AD, network infrastructure (DNS, DHCP, NFS, LDAP, Apache and IIS web services)
Certifications: Certified Systems Engineer, Certified Network Engineer

PUBLICATIONS

- G. Matthew Fricke, Joshua P Hecker, Antonio Griego, Linh Tran, and Melanie E Moses. A Distributed Deterministic Spiral Search Algorithm for Robot Swarms. In *Proceedings of the International Conference on Intelligent Robots and Systems*. IEEE, 2016a.
- G. Matthew Fricke, Joshua Hecker, Judy Cannon, and Melanie Moses. Immune-inspired search strategies for robot swarms. *Robotica*, 2016b.
- G. Matthew Fricke, Kenneth Letendre, Melanie Moses, and Judy Cannon. Persistence and adaptation in immunity: T cells balance the extent and thoroughness of search. *PLoS Computational Biology*, 2016c.
- G. Matthew Fricke, Joshua P Hecker, Sarah R Black, Judy L Cannon, and Melanie E Moses. Distinguishing Adaptive Search From Random Search in Robots and T cells. In *Proceedings of the Conference on Genetic and Evolutionary Computation*. ACM, 2015. doi: 10.1145/2739480.2754794.
- Melanie Moses, Tatiana Flanagan, Kenneth Letendre, and Matthew Fricke. Ant colonies as a model of human computation. In Pietro Michelucci, editor, *Handbook of Human Computation*, pages 25–39. Springer, New York, NY, 2014. doi: 10.1007/978-1-4614-8806-4.
- G. Matthew Fricke, François Asperti-Boursin, Joshua Hecker, Judy Cannon, and Melanie Moses. From Microbiology to Microcontrollers: Robot Search Patterns Inspired by T Cell Movement. In *Advances in Artificial Life, ECAL*, volume 12, pages 1009–1016, 2013.

Tatiana P. Flanagan, Kenneth Letendre, William R. Burnside, G. Matthew Fricke, and Melanie E. Moses. Quantifying the effect of colony size and food distribution on harvester ant foraging. *PLoS ONE*, 2012. doi: 10.1371/journal.pone.0039427.

Tatiana P. Flanagan, Kenneth Letendre, William R. Burnside, G. Matthew Fricke, and Melanie E. Moses. How ants turn information into food: A case study in distributed search. In *IEEE Symposium on Artificial Life (ALIFE)*, pages 178 – 185. IEEE, 2011. doi: 10.1109/ALIFE.2011.5954650.

Bin Hu, G. Matthew Fricke, James R. Faeder, Richard G. Posner, and William S. Hlavacek. Getbonnie for building, analyzing, and sharing rule-based models. *Bioinformatics*, 2009. doi: 10.1093/bioinformatics/btp173.

G. Matthew Fricke and James L. Thomas. Receptor aggregation by intermembrane interactions: A monte carlo study. *Biophysical Chemistry*, 2006. doi: 10.1016/j.bpc.2005.09.019.

CONFERENCES G. Matthew Fricke and Melanie Moses, “Biologically-Inspired Distributed Spatial Search for Ground-Based Foraging Swarms”, 36th Annual ACM Symposium on Principles of Distributed Computing, Washington, DC, 2017

G. Matthew Fricke, Joshua P. Hecker, Antonio Griego, Linh Tran, and Melanie Moses, “A Distributed Deterministic Spiral Search Algorithm for Swarms”, 29th Annual International Conference on Intelligent Robots and Systems, Daejeon, South Korea, 2016 (presenting author)

Kirubel Tadesse, George Matthew Fricke, Joshua Peter Hecker, Melanie Moses, “April Tag Detection: Calculating Distance Use ROS Transform Package”, 29th Annual International Conference on Intelligent Robots and Systems”, Daejeon, South Korea, 2016 (poster)

G. Matthew Fricke, “Swarmathon: Training the next generation of ROS programmers”, RosCon 2016 Lightning Talks, Seoul, South Korea, 2016 (presenter)

G. Matthew Fricke, Joshua P. Hecker, “Swarmathon Technical Tutorial: Extended Kalman Filters”, Robotics: Science and Systems (RSS), Ann Arbor, MI, 2016, (presenter)

G. Matthew Fricke, Joshua P. Hecker, Melanie E. Moses, “The Adaptive Lévy Search Algorithm Applied to a Robot Swarm”, Quantifying Complex Transport with Lévy Walks: From Cold Atoms to Humans and Robots, Physikzentrum Bad Honnef, 2016 (poster)

Byrum, J.R., Tafoya, J., Fricke, G.M., Moses, M.E., Cannon, J.L. “Quantitating dendritic cell distribution in lymph nodes”, American Association of Immunologists, Seattle, WA. 2016 (poster)

G. Matthew Fricke, Josh P. Hecker, Antonio Griego, Linh Tran, and Melanie Moses, “Spiral Search in Robot Swarms”, 12th Annual UNM Computer Science Student Conference, 2016, Albuquerque, NM. (presenting author)

G. Matthew Fricke, Judy Cannon and Melanie Moses, “Efficiency of T cell Search in Lymph Nodes”, 12th Annual Conference on Complex Systems, Phoenix, AZ. 2016

(presenting author)

G. Matthew Fricke, Judy Cannon, François Asperti-Boursin and Melanie Moses, “T cell Stochastic Search Patterns”, Stochastic Single-Cell Dynamics in Immunology Experimental and Theoretical Approaches, Workshop, Netherlands Royal National Academy, Amsterdam, 2015 (poster)

G. Matthew Fricke, Judy Cannon, and Melanie Moses, “T cell Search Inspired Computation”, Motility in the Immune System: From Microscopic Movement to Macroscopic Function, Workshop, Santa Fe Institute, Santa Fe, NM, 2015 (presenter)

Tatiana Flanagan, G. Matthew Fricke, Joshua P. Hecker, Kenneth Letendre, Drew Levin, Stephanie Forrest, Deborah Gordon and Melanie Moses, “Using information to improve collective search”, 12th Annual Conference on Complex Systems, Phoenix, AZ, 2015, (presentation, author)

G. Matthew Fricke, Sarah R. Black, Joshua P. Hecker, Judy L. Cannon, and Melanie E. Moses. “Distinguishing Adaptive Search from Random Search in Robots and T cells”, 17th Annual Genetic and Evolutionary Computation Conference, Madrid, 2015 (presenting author)

G. Matthew Fricke, François Asperti-Boursin, Judy Cannon, and Melanie Moses, “Efficiency and Robustness of T cell Search”, 3rd Biennial Conference on Systems Approaches to Immunology and Infectious Diseases, Santa Fe, NM, 2014 (poster)

G. Matthew Fricke, François Asperti-Boursin, Judy Cannon, and Melanie Moses, “T cell Motility and Robotic Search”, 10th Annual UNM Computer Science Student Conference, 2014 Apr 18th, Albuquerque, NM, (presenting author)

Tatiana M. Paz, G Matthew Fricke, Kenneth Letendre, William R. Burnside and Melanie Moses, “Effects of colony size and resource distribution on the foraging behavior of three species of desert harvester ants” 94th Ecological Society of America Annual Meeting, Albuquerque, NM, 2009 (poster)

Andy Claiborne and G. Matthew. Fricke and L. Lopes and George Luger, “Emergent Representation in a Robot Control Architecture”, 2nd Annual UNM-NASA PURSUE Conference on Autonomous Control Systems, 2000, Albuquerque, NM. UNM Computer Science Technical Report TR-CS-2000-55, (presentation, author)

**COMMUNITY
SERVICE**

Reviewer for *Swarm Intelligence*.

Automatica.

Journal of Theoretical Biology.

ACM Symposium on Principles of Distributed Computing.

DARS: Distributed Autonomous Robotic Systems.

IROS: IEEE/RSJ Intl. Conference on Intelligent Robots and Systems.

Alife: Conference on the Synthesis and Simulation of Living Systems.

Workshop Organizer, Robotics Science and Systems Conference, Workshop Hackathon: “Become a swarm programmer overnight”. Massachusetts Institute of Technology, 2017.

Contributor to the Repp package for R: the Project for Statistical Computing
Volunteer, UNM/VEX Robotics Competition, 2014

Instructor, UNM Computer Science Middle School Outreach, 2014, 2015
Judge, Senior Mathematics, Senior Computer Science, Annual Central NM Regional Science & Engineering Research Challenge, 2012, 2013, 2016 and 2017
Volunteer Grader, Public Service Company of New Mexico State Math Competition, 2012

PROF. ORGS. Association for Computing Machinery (ACM)
International Association for Artificial Life (ALIFE)
Institute of Electrical and Electronics Engineers (IEEE)
Complex Systems Society (CSS)

GRANTS AND AWARDS Best Poster, Quantifying Complex Transport with Lévy Walks: From Cold Atoms to Humans and Robots, 2016
NSF Travel Grant distributed by Rice University R3G410, 2016
1st place 12th Annual UNM Computer Science Graduate Conference, 2016
University of New Mexico Office of Graduate Studies Travel Grant, 2015
2nd place 10th Annual UNM Computer Science Graduate Conference, 2014
1st place Tech New Mexico Competition 2013
1st place, Student Paper Competition, IEEE Symposium on Artificial Life, 2011

REFERENCES Joshua Hecker (UNM-NASA Technical Lead) jhecker@cs.unm.edu
University of New Mexico (505) 710-7602
Computer Science Dept.

Melanie Moses (Associate Professor) melaniem@cs.unm.edu
University of New Mexico (505) 277-3112
Computer Science Dept.

Bill Hlavacek (Scientist) wish@lanl.gov
Los Alamos National Labs (505) 665 1355
Dept of Theoretical Biology and Biophysics
Center for Non-linear Studies